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explains the situation  
in more detail.

**Iso 10218 2 2011 07**  
ISO 10218-2:2011 also  
specifies requirements  
for the industrial robot  
system as part of an  
integrated  
manufacturing system.  
ISO 10218-2:2011 does  
not deal specifically  
with hazards  
associated with  
processes (e.g. laser  
radiation, ejected  
chips, welding smoke).

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Other standards can be applicable to these process hazards.

## **ISO - ISO 10218-2:2011 - Robots and robotic devices ...**

The Standard EN ISO 10218-2 was published in July 2011 by Technical Committee ISO/TC 184 in collaboration with Technical Committee CEN/TC 310.. This is a technical standard of

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type C, regarding robots and robotic devices.. The scope of the Standard is to specify the safety requirements for the integration of industrial robots and industrial robot system.

## **EN ISO 10218-2: Robot systems and integration**

ISO/DIS 10218-2  
Robotics — Safety ...  
30.60 2018-01-07.

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ISO 10218-2 First  
edition 2011-07-01  
Robots and robotic  
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2: Robot systems and  
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— Exigences de  
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industriels — Partie 2:  
Systèmes robots et  
intégration

**INTERNATIONAL ISO**  
**This is a preview of**

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## **ISO 10218-2:2011 ...**

ISO 10218-2:2011 describes the basic hazards and hazardous situations identified with these systems, and provides requirements to eliminate or adequately reduce the risks associated with these hazards. ISO 10218-2:2011 also specifies requirements for the industrial robot system as part of an integrated

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manufacturing system.

## **EN ISO 10218-2:2011**

ISO 10218-2:2011(en)

× ISO

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Robots and robotic

devices ? Safety

requirements for

industrial robots ? Part

2: Robot systems and

integration. Comparar.

Seguir. Índice. Scope.

Normative references.

Terms and definitions.

Hazard identification

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and risk assessment.  
General. Layout  
design.

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ISO 10218 -1:2011 &  
ISO 10218 -2:2011 .  
Vocabulary lesson •A  
collaborative robot is a  
robot that can be used  
in a collaborative  
operation

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- Collaborative operation (Part 1, 3.4)
- state in which purposely designed robots work in direct cooperation with a human within a defined

## **Safety Standards and Collaborative Robots**

ISO 10218 SS ISO  
10218 . ISO 10218-2  
SS ISO 10218-2 . 3. The  
comma has been used  
throughout as a  
decimal marker

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whereas in Singapore Standards it is a practice to use a full point on the baseline as the decimal marker. This standard is expected to be used by machine builders, system builders, precision engineering

## **SINGAPORE STANDARD Robots and robotic devices Safety ...**

- ISO 10218-1 Robots & -2 Integration

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published in 2011. •  
These standards are  
based on the 1999  
R15.06. • 1999 R15.06  
was torn into two  
parts: robot  
manufacturer (-1) and  
requirements for  
systems (with end-  
effectors) & integrators  
(-2). • USA provided  
input to the ISO 10218  
standards  
development:

## **Robot Safety Standard Update -**

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## **Robotics Online**

ISO 10218-2:2011 describes the basic hazards and hazardous situations identified with these systems, and provides requirements to eliminate or adequately reduce the risks associated with these hazards. ISO 10218-2:2011 also specifies requirements for the industrial robot system as part of an integrated

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manufacturing system.

## **ISO 10218-2:2011 - Standards New Zealand**

ISO 10218-2:2011 describes the basic hazards and hazardous situations identified with these systems, and provides requirements to eliminate or adequately reduce the risks associated with these hazards. ISO 10218-2:2011 also

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specifies requirements for the industrial robot system as part of an integrated manufacturing system.

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## **ISO 10218-2:2011 - Estonian Centre for Standardisation**

31 July 2011 Normative  
References(Required to  
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this standard) ISO 4414  
, ISO 4413 , IEC  
61496-1 , ISO 13856 ,  
IEC 61800-5-2 , ISO  
10218-1 , IEC  
62061:2005 , ISO  
14119 , ISO 14122 ,  
ISO 8995-1 , IEC/TS  
62046 , ISO  
13849-1:2006 , ISO  
13857 , ISO 13850 ,

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ISO 13855 , ISO 13854  
, ISO 12100 , ISO  
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ISO 14118 , ISO 9946 ,  
IEC 60204-1

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ISO 10218-2:2011  
describes the basic  
hazards and hazardous  
situations identified  
with these systems,  
and provides  
requirements to  
eliminate or  
adequately reduce the

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risks associated with these hazards. ISO 10218-2:2011 also specifies requirements for the industrial robot system as part of an integrated manufacturing system.

## **ISO 10218-2:2011 - Normadoc**

This is the third edition of CAN/CSA-Z434, Industrial robots and robot systems, which is an adoption, with Canadian deviations, of

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the ISO (International Organization for Standardization) Standards 10218-1 (second edition, 2011-07-01), Robots and robotic devices - Safety requirements for industrial robots - Part 1: Robots, and 10218-2 (first edition, 2011-07-01), Robots and robotic devices ...

**CAN/CSA Z434-2014  
- CAN/CSA-Z434-14 -  
Industrial robots ...**

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